

# **The Heat and the Wave Equation**

by

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## PHYSICAL BACKGROUND

### 1. The wave equation in one dimension

In this section we derive the equations of motion for a vibrating string and a vibrating membrane.

Consider a string which we assume to be described as the graph of a function of  $x$  (space) and  $t$  (time):

$$y = u(x, t).$$

Vertical external forces acting on a piece of the string between  $x = a$  and  $x = b$ ,  $(a, b)$  for short, may be described as

$$\int_a^b f(x, t) dx \quad (\text{in positive } y\text{-direction}).$$

Here  $f(x, t)$  is the force per unit of length, and  $u_x = \partial u / \partial x$  is assumed to be small, so that the arc length

$$\sqrt{1 + \left(\frac{\partial u}{\partial x}\right)^2} dx \approx dx.$$

Now what are the internal forces acting on  $(a, b)$ ?

In  $x = a$  we have a tangential force proportional to the strain,

$$\vec{F}_a = -\sigma(a) \frac{1}{\sqrt{1 + u_x(a)^2}} \begin{pmatrix} 1 \\ u_x(a) \end{pmatrix}.$$

Similarly, at  $x = b$ ,

$$\vec{F}_b = \sigma(b) \frac{1}{\sqrt{1 + u_x(b)^2}} \begin{pmatrix} 1 \\ u_x(b) \end{pmatrix}.$$

Assuming again that  $u_x$  is small, the total internal force acting on  $(a, b)$  is given by

$$\vec{F} = \sigma(b) \begin{pmatrix} 1 \\ u_x(b) \end{pmatrix} - \sigma(a) \begin{pmatrix} 1 \\ u_x(a) \end{pmatrix}.$$

Newton's law says that the combined forces determine the change of impuls moment. Ignoring motion in the  $x$ -direction, we conclude that  $\sigma(a) = \sigma(b)$ , and since  $a, b$  where arbitrary,

$$\sigma(x) \equiv \sigma \quad \text{is constant.}$$

Thus the impuls moment of  $(a, b)$  has only a  $y$ -component, given by

$$\int_a^b \rho(x) \frac{\partial u}{\partial t}(x, t) dx,$$

where  $\rho(x)$  is the mass density of the string per unit length, so that

$$\frac{d}{dt} \int_a^b \rho(x) \frac{\partial u}{\partial t}(x, t) dx = \sigma(b) \frac{\partial u}{\partial x}(b, t) - \sigma(a) \frac{\partial u}{\partial x}(a, t) + \int_a^b f(x, t) dx,$$

or, assuming also  $\rho(x) \equiv \rho$  is a constant,

$$\int_a^b \rho \frac{\partial^2 u}{\partial t^2}(x, t) dx = \int_a^b \frac{\partial}{\partial x} \sigma \frac{\partial u}{\partial x}(x, t) dx + \int_a^b f(x, t) dx.$$

Again, since  $a$  and  $b$  are arbitrary, we conclude that

$$\rho \frac{\partial^2 u}{\partial t^2} = \sigma \frac{\partial^2 u}{\partial x^2} + f, \quad (1.1)$$

which is the *one-dimensional inhomogeneous wave equation*.

## 2. The wave equation in more dimensions

Next we consider a vibrating membrane. We examine where the derivation above has to be adjusted. Instead of  $y = u(x, t)$  we have

$$z = u(x, y, t),$$

and instead of  $(a, b)$  we take a small open disk  $D$  in the  $(x, y)$ -plane. The horizontal internal force acting on the piece corresponding to  $D$  is given by, again assuming that  $u_x$  and  $u_y$  are small,

$$\oint_{\partial D} \sigma(x, y) \nu(x, y) dS,$$

Here  $\nu$  is the outward normal,  $dS$  is the arc length,  $\partial D$  is the boundary of  $D$ , and  $\sigma$  is the strain. By the vector valued integral version of the divergence theorem, this equals

$$\int_D \nabla \sigma(x, y) d(x, y),$$

which has to be zero again, because we neglect motion in the horizontal directions. But  $D$  is arbitrary so  $\nabla \sigma \equiv 0$ , i.e.  $\sigma(x, y) = \sigma$  is constant. The vertical internal force acting on  $D$  is then

$$\sigma \oint_{\partial D} \nabla u(x, y, t) \cdot \nu(x, y) dS =$$

(by the divergence theorem)

$$\sigma \int_D \Delta u(x, y, t) d(x, y).$$

Here  $\nabla$  and  $\Delta$  act only on  $x$  and  $y$ , but not on  $t$ . The *inhomogeneous wave equation in two (and in fact any  $n$ ) dimensions* thus reads

$$\rho \frac{\partial^2 u}{\partial t^2} = \sigma \Delta u + f. \quad (2.1)$$

### 3. Conservation laws and diffusion

Let  $\Omega \subset \mathbb{R}^3$  be a bounded domain, i.e. a bounded open connected set. We assume  $\Omega$  is filled with some sort of *diffusive* material, with concentration given by

$$c = c(x, t) = c(x_1, x_2, x_3, t),$$

where  $x$  is space,  $t$  is time. Motion is then usually described by the *mass flux*

$$\vec{\Phi} = \begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \Phi_3 \end{pmatrix} = \vec{\Phi}(x, t).$$

The direction of  $\vec{\Phi}$  coincides with the direction of the motion, and its magnitude says how much mass flows through a plane perpendicular to  $\vec{\Phi}$ , per unit of surface area.

If we consider any ball  $B$  contained in  $\Omega$  and compute what comes out of  $B$  per unit of time, we find

$$\begin{aligned} \oint_{\partial B} \Phi(x, t) \nu(x) dS(x) &= \int_B \operatorname{div} \Phi(x, t) dx = \\ &= \int_B \left\{ \frac{\partial \Phi_1(x, t)}{\partial x_1} + \frac{\partial \Phi_2(x, t)}{\partial x_2} + \frac{\partial \Phi_3(x, t)}{\partial x_3} \right\} d(x_1, x_2, x_3). \end{aligned}$$

Assuming that new material is being produced in  $\Omega$ , and that per unit of time the production rate in any disk  $B$  is given by

$$\int_B q(x, t) dx,$$

we have by the *conservation of mass principle*

$$\frac{d}{dt} \int_B c(x, t) dx = - \int_B \operatorname{div} \Phi(x, t) dx + \int_B q(x, t) dt.$$

Since  $B$  was arbitrary, we find

$$\frac{\partial c}{\partial t} = -\operatorname{div}\Phi(x, t) + q(x, t), \quad (3.1)$$

which is commonly called a *conservation law*.

This conservation law has to be combined with some sort of second relation between the concentration  $c$  and the flux  $\Phi$  in order to arrive at a single equation for  $c$ . An example of such a relation is the principle of *diffusion* which says that mass flows from higher to lower concentrations, i.e. the flux  $\Phi$  and the gradient of the concentration, point in opposite directions:

$$\vec{\Phi} = -D\nabla C. \quad (3.2)$$

Here  $D > 0$  is the diffusion coefficient, which may depend on space, time, etc. In the simplest case  $D$  is a constant. Substituting this second relation in the conservation law we obtain, if  $D$  is a constant,

$$\frac{\partial c}{\partial t} = \operatorname{div} D\nabla c + q = D\Delta c + q. \quad (3.3)$$

Because a similar derivation can be given for the flow of heat in a physical body, this equation is often called the *inhomogeneous heat equation*.

## PART 2: THE WAVE EQUATION

### 4. The Cauchy problem in one space dimension

For  $u = u(x, t)$  we consider the equation

$$u_{tt} - c^2 u_{xx} = 0, \quad (4.1)$$

where  $c \in \mathbb{R}^+$  is fixed and  $x$  and  $t$  are real variables. We change variables by setting

$$\xi = x + ct, \quad \eta = x - ct. \quad (4.2)$$

Then

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \xi} + \frac{\partial}{\partial \eta} \quad \text{and} \quad \frac{\partial}{\partial t} = c \frac{\partial}{\partial \xi} - c \frac{\partial}{\partial \eta},$$

so that

$$\begin{aligned} \frac{\partial^2}{\partial t^2} - c^2 \frac{\partial^2}{\partial x^2} &= c^2 \frac{\partial^2}{\partial \xi^2} - 2c^2 \frac{\partial^2}{\partial \xi \partial \eta} + c^2 \frac{\partial^2}{\partial \eta^2} \\ -c^2 \frac{\partial^2}{\partial \xi^2} - 2c^2 \frac{\partial^2}{\partial \xi \partial \eta} - c^2 \frac{\partial^2}{\partial \eta^2} &= -(2c)^2 \frac{\partial^2}{\partial \xi \partial \eta}, \end{aligned}$$

and (4.1) reduces to

$$u_{\xi\eta} = 0. \quad (4.3)$$

Formally then every function of the form

$$u(x, t) = f(\xi) + g(\eta) = f(x + ct) + g(x - ct), \quad (4.4)$$

is a solution. The lines  $\xi = \text{constant}$  and  $\eta = \text{constant}$  are called *characteristics*.

Next consider the initial value problem

$$(CP) \begin{cases} u_{tt} - c^2 u_{xx} = 0 & x, t \in \mathbb{R}; \\ u(x, 0) = \alpha(x) & x \in \mathbb{R}; \\ u_t(x, 0) = \beta(x) & x \in \mathbb{R}. \end{cases}$$

This is usually called the *Cauchy problem* for the wave equation in one space dimension. To solve (CP) for given functions  $\alpha$  and  $\beta$  we use (4.4). Thus we have to find  $f$  and  $g$  such that

$$\alpha(x) = u(x, 0) = f(x) + g(x) \quad \text{and} \quad \beta(x) = u_t(x, 0) = cf'(x) - cg'(x).$$

It is no restriction to assume that  $f(0) - g(0) = 0$ . Hence

$$f(x) - g(x) = \frac{1}{c} \int_0^x \beta(s) ds \quad \text{and} \quad f(x) + g(x) = \alpha(x).$$

Solving for  $f$  and  $g$  we obtain

$$f(x) = \frac{1}{2}\alpha(x) + \frac{1}{2c} \int_0^x \beta(s) ds \quad \text{and} \quad g(x) = \frac{1}{2}\alpha(x) - \frac{1}{2c} \int_0^x \beta(s) ds.$$

Here the only restriction on the functions  $\alpha$  and  $\beta$  is that the latter one has to be locally integrable. Using (4.2) and (4.4) we conclude that

$$u(x, t) = \frac{1}{2} \{ \alpha(x + ct) + \alpha(x - ct) \} + \frac{1}{2c} \int_{x-ct}^{x+ct} \beta(s) ds. \quad (4.5)$$

Clearly,  $u$  defined as such, satisfies  $u(x, 0) = \alpha(x)$ , and if  $\alpha$  is differentiable, and  $\beta$  continuous, then

$$u_t(x, t) = \frac{1}{2} \{ c\alpha'(x + ct) - c\alpha'(x - ct) \} + \frac{1}{2c} \{ c\beta(x + ct) + c\beta(x - ct) \},$$

so that  $u_t(x, 0) = \beta(x)$ .

For the (1.1) to be satisfied in a classical way, i.e. for  $u_{tt}$  and  $u_{xx}$  to be continuous, we need  $\alpha$  to be twice and  $\beta$  to be once continuously differentiable. We summarize these results in the following theorem.

**4.1 Theorem** Let  $\alpha \in C^2(\mathbb{R})$  and  $\beta \in C^1(\mathbb{R})$ . Then problem (CP) has a unique solution  $u \in C^2(\mathbb{R} \times \mathbb{R})$ , given by

$$u(x, t) = \frac{1}{2} \{ \alpha(x + ct) + \alpha(x - ct) \} + \frac{1}{2c} \int_{x-ct}^{x+ct} \beta(s) ds.$$

The right hand side of this expression is defined for all  $\alpha : \mathbb{R} \rightarrow \mathbb{R}$  and all locally integrable  $\beta : \mathbb{R} \rightarrow \mathbb{R}$ .

**Proof** The derivation of the formula is correct if  $u$  is a twice continuously differentiable solution and it is easy to check that under the hypotheses  $u$  as defined in the theorem is indeed such a solution. ■

**4.2 Corollary** Suppose  $\text{supp } \alpha \cup \text{supp } \beta \subset [A, B]$ . Then  $\text{supp } u \subset [A - ct, B + ct]$ , for  $t > 0$ ,

## 5. The inhomogeneous wave equation in dimension one

Next we consider the Cauchy problem for the inhomogeneous wave equation,

$$(CP_i) \begin{cases} u_{tt} - c^2 u_{xx} = \varphi(x, t) & x, t \in \mathbb{R}; \\ u(x, 0) = \alpha(x) & x \in \mathbb{R}; \\ u_t(x, 0) = \beta(x) & x \in \mathbb{R}, \end{cases}$$

for given functions  $\alpha, \beta, \varphi$ . We assume  $\varphi$  is integrable.

We shall derive a representation formula for the solution of  $(CP_i)$ . To do so, fix  $x_0$  and  $t_0 > 0$ , and consider the triangle  $G$  in  $\mathbb{R} \times \mathbb{R}$  bounded by the segments  $C_1 = \{x - x_0 = c(t - t_0), 0 < t < t_0\}$ ,  $C_2 = \{x - x_0 = -c(t - t_0), 0 < t < t_0\}$ , and  $I = \{t = 0, x_0 - ct_0 < x < x_0 + t_0\}$ . Assume  $u$  is smooth and satisfies

$$u_{tt} - c^2 u_{xx} = \text{div} \begin{pmatrix} -c^2 u_x \\ u_t \end{pmatrix} = \varphi(x, t). \quad (5.1)$$

Here  $x$  is the first, and  $t$  the second coordinate. Applying the divergence theorem we have

$$\int \int_G \varphi(x, t) dx dt = \oint_{\partial G} \begin{pmatrix} -c^2 u_x \\ u_t \end{pmatrix} \cdot \nu dS =$$

(where  $\nu$  is the outward normal on  $\partial G$ )

$$\oint_{\partial G} (-c^2 u_x dt - u_t dx) = \int_{C_1} + \int_{C_2} + \int_I (-c^2 u_x dt - u_t dx) =$$

(using  $dx = cdt$  along  $C_1$  and  $dx = -cdt$  along  $C_2$ )

$$\begin{aligned} & \int_{C_1} (-cu_x dx - cu_t dt) + \int_{C_2} (cu_x dx + cu_t dt) + \int_I -u_t dx = \\ & -c\alpha(x_0 - ct_0) + 2cu(x_0, t_0) - c\alpha(x_0 + ct_0) - \int_{x_0 - ct_0}^{x_0 + ct_0} \beta(s) ds. \end{aligned}$$

Thus problem  $(CP_i)$  should have as a solution

$$u(x, t) = \frac{1}{2} \{ \alpha(x - ct) + \alpha(x + ct) \} + \frac{1}{2c} \int_{x - ct}^{x + ct} \beta(s) ds + \frac{1}{2c} \int_0^t \int_{x - c(t - \tau)}^{x + c(t - \tau)} \varphi(\xi, \tau) d\xi d\tau.$$

We have already investigated for which  $\alpha$  and  $\beta$  this makes sense, so consider the new term, which we denote by

$$u_p(x, t) = \frac{1}{2c} \int_0^t \int_{x - c(t - \tau)}^{x + c(t - \tau)} \varphi(\xi, \tau) d\xi d\tau. \quad (5.2)$$

For all locally integrable  $\varphi$  the function  $u_p$  is well defined as a function of  $x \in \mathbb{R}$  and  $t \in \mathbb{R}$ , and since  $\varphi$  is integrated over a domain in  $\mathbb{R} \times \mathbb{R}$  with continuously varying boundary, it is clear that  $u_p \in C(\mathbb{R} \times \mathbb{R})$ , and that  $u_p(x, 0) = 0$  for all  $x \in \mathbb{R}$ . Also, the measure of  $G$  equals  $ct^2$ , so that for locally bounded  $\varphi$ ,

$$u_p(x, t) = O(t^2) \quad \text{as } t \rightarrow 0,$$

uniformly on bounded  $x$ -intervals. In particular,

$$\frac{\partial u_p}{\partial t}(x, 0) = 0,$$

for all  $x \in \mathbb{R}$ .

Next we give conditions on  $\varphi$  for  $u_p$  to be a classical solution of the inhomogeneous wave equation. We assume that  $\varphi \in C(\mathbb{R} \times \mathbb{R})$ . Then

$$u_p(x, t) = \frac{1}{2c} \int_0^t g(x, t, \tau) d\tau; \quad g(x, t, \tau) = \int_{x - c(t - \tau)}^{x + c(t - \tau)} \varphi(\xi, \tau) d\xi,$$

so that

$$\frac{\partial g}{\partial x}(x, t, \tau) = \varphi(x + c(t - \tau), \tau) - \varphi(x - c(t - \tau), \tau),$$

and

$$\frac{\partial g}{\partial t}(x, t, \tau) = c\varphi(x + c(t - \tau), \tau) + c\varphi(x - c(t - \tau), \tau).$$



Thus  $g$  is differentiable with respect to  $x$  and  $t$ , with partial derivatives continuous in  $x, t$  and  $\tau$ . Hence

$$\begin{aligned}\frac{\partial u_p}{\partial t}(x, t) &= \frac{1}{2c}g(x, t, t) + \frac{1}{2c} \int_0^t \frac{\partial g}{\partial t}(x, t, \tau) d\tau \\ &= \frac{1}{2} \int_0^t \{\varphi(x + c(t - \tau), \tau) + \varphi(x - c(t - \tau), \tau)\} d\tau,\end{aligned}$$

which is continuous because  $\varphi$  is. Similarly we find that

$$\begin{aligned}\frac{\partial u_p}{\partial x}(x, t) &= \frac{1}{2c} \int_0^t \frac{\partial g}{\partial x}(x, t, \tau) d\tau = \\ &= \frac{1}{2c} \int_0^t \{\varphi(x + c(t - \tau), \tau) - \varphi(x - c(t - \tau), \tau)\} d\tau\end{aligned}$$

is continuous. We conclude that  $u_p \in C^1(\mathbb{R} \times \mathbb{R})$ .

If we want  $u_p$  to be in  $C^2(\mathbb{R} \times \mathbb{R})$ , we need more regularity on  $\varphi$  because we have to differentiate once more under the integral sign. This is allowed if  $\varphi_x$  is continuous. Then

$$\frac{\partial^2 u_p}{\partial t^2}(x, t) = \varphi(x, t) + \frac{1}{2} \int_0^t \{c\varphi_x(x + c(t - \tau), \tau) - c\varphi_x(x - c(t - \tau), \tau)\} d\tau,$$

while

$$\frac{\partial^2 u_p}{\partial x^2}(x, t) = \frac{1}{2c} \int_0^t \{\varphi_x(x + c(t - \tau), \tau) - \varphi_x(x - c(t - \tau), \tau)\} d\tau,$$

so that indeed  $u_p$  is a solution of the inhomogeneous wave equation.

**5.1 Theorem** Suppose  $\alpha \in C^2(\mathbb{R})$ ,  $\beta \in C^1(\mathbb{R})$ ,  $\varphi \in C(\mathbb{R} \times \mathbb{R})$ , and  $\varphi_x \in C(\mathbb{R} \times \mathbb{R})$ . Then problem  $(CP_i)$  has a unique solution  $u \in C^2(\mathbb{R} \times \mathbb{R})$ , which for  $t > 0$  is given by

$$u(x, t) = \frac{1}{2} \{\alpha(x - ct) + \alpha(x + ct)\} + \frac{1}{2c} \int_{x-ct}^{x+ct} \beta(\xi) d\xi + \frac{1}{2c} \int \int_{G(x, t)} \varphi(\xi, \tau) d\xi d\tau,$$

where

$$G(x, t) = \{(\xi, \tau), 0 \leq \tau \leq t, |\xi - x| \leq c(t - \tau)\}.$$

**Proof** The derivation above is correct if  $u$  is a twice continuously differentiable solution and we have seen that under the hypotheses  $u$  as defined in the theorem is indeed such a solution. ■

## 6. Initial boundary value problems

We now consider the inhomogeneous wave equation

$$u_{tt} = c^2 u_{xx} + \varphi \quad (6.1)$$

on the strip  $\{(x, t) : a < x < b\}$ . Initial conditions are again of the form

$$(IC) \quad \begin{cases} u(x, 0) = \alpha(x) & x \in (a, b); \\ u_t(x, 0) = \beta(x) & x \in (a, b). \end{cases}$$

For (lateral) boundary conditions one can take any of the following four combinations

$$\begin{array}{ll} (DD) & \begin{cases} u(a, t) = A(t) \\ u(b, t) = B(t) \end{cases} & (DN) & \begin{cases} u(a, t) = A(t) \\ u_x(b, t) = B(t) \end{cases} \\ (ND) & \begin{cases} u_x(a, t) = A(t) \\ u(b, t) = B(t) \end{cases} & (NN) & \begin{cases} u_x(a, t) = A(t) \\ u_x(b, t) = B(t) \end{cases} \end{array}$$

**6.1 Theorem** For any  $T > 0$  there is atmost one solution  $u \in C^2([a, b] \times [0, T])$  of (6.1) satisfying the initial conditions (IC) as well as the lateral boundary conditions (DD), (ND), (DN) or (NN).

**Proof** Assuming the existence of two different solutions we obtain, by subtraction, the existence of a nontrivial solution  $u$  with boundary conditions given by  $A(t) \equiv B(t) \equiv 0$ , and  $\alpha(x) \equiv \beta(x) \equiv 0$ . Define the "energy" integral

$$E(t) = \frac{1}{2} \int_a^b \{c^2 u_x^2 + u_t^2\} dx.$$

Then for all  $t \geq 0$ ,

$$\begin{aligned} \frac{dE}{dt}(t) &= \int_a^b \{c^2 u_x u_{xt} + u_t u_{tt}\} dx = \int_a^b \{c^2 u_x u_{xt} + u_t c^2 u_{xx}\} dx \\ &= c^2 \int_a^b \frac{\partial}{\partial x} (u_x u_t) dx = c^2 [u_x u_t]_{x=a}^{x=b} = 0. \end{aligned}$$

Thus  $E(t) \equiv E(0) = 0$ , so that  $u \equiv 0$ .

Contradiction, because we assumed  $u$  to be nontrivial. ■

For the construction of solutions we use the following lemma.

**6.2 Lemma** Let  $u \in C^2(\vartheta)$  for some open subset  $\vartheta$  of  $\mathbb{R} \times \mathbb{R}$ . Then  $u$  is a solution of  $u_{tt} = u_{xx}$  in  $\vartheta$ , if and only if  $u$  satisfies the difference equation

$$u(x - k, t - h) + u(x + k, t + h) = u(x - h, t - k) + u(x + h, t + k)$$

for all  $x, t, k, h$  such that the rectangle  $R$  with vertices  $A = (x - k, t - h)$ ,  $B = (x + h, t + k)$ ,  $C = (x + k, t + h)$ , and  $D = (x - h, t - k)$  is contained in  $\vartheta$ . ( $R$  is called a characteristic rectangle, because its boundary consists of characteristics.)

**Proof** Suppose  $u$  solves  $u_{tt} = u_{xx}$ . Then  $u$  is of the form  $u(x, t) = f(x+t) + g(x-t)$ . Since

$$f(A) + f(C) = f(x + t - h - k) + f(x + t + h + k) = f(B) + f(D),$$

and

$$g(A) + g(C) = g(x - k - t + h) + g(x + k - t - h) = g(B) + g(D),$$

it follows that  $u(A) + u(C) = u(B) + u(D)$ .

Conversely, suppose  $u$  satisfies the difference equation for all characteristic rectangles  $R \subset \vartheta$ . Put  $h = 0$ , then

$$\frac{u(x - k, t) - 2u(x, t) + u(x + k, t)}{k^2} = \frac{u(x, t - k) - 2u(x, t) + u(x, t + k)}{k^2}.$$

Using Taylor's theorem with respect to the variable  $k$  in the numerators, we obtain, as  $k \rightarrow 0$ , that  $u_{tt} = u_{xx}$ . This completes the proof of the lemma. ■

With this lemma we can obtain a solution of the inhomogeneous wave equation satisfying initial conditions (IC) and lateral boundary conditions (DD).

**6.3 Theorem** Let  $\alpha \in C^2([a, b])$ ,  $\beta \in C^1([a, b])$ ,  $A, B \in C^2([0, \infty])$ ,  $\varphi, \varphi_x \in C([a, b] \times [0, \infty])$ , and suppose that the following six compatibility conditions are satisfied:

$$\begin{aligned} A''(0) &= c^2 \alpha''(a) + \varphi(a, 0) ; \alpha(a) = A(0) ; A'(0) = \beta(a) ; \\ B''(0) &= c^2 \alpha''(b) + \varphi(b, 0) ; \alpha(b) = B(0) ; B'(0) = \beta(b). \end{aligned}$$

Then the problem

$$\begin{cases} u_{tt} - c^2 u_{xx} = \varphi & a < x < b, t > 0; \\ u(a, t) = A(t) ; u(b, t) = B(t) & t > 0; \\ u(x, 0) = \alpha(x) ; u_t(x, 0) = \beta(x) & a \leq x \leq b, \end{cases}$$

has a unique solution  $u \in C^2([a, b] \times [0, \infty))$ .

**Proof** It suffices to prove existence. First we reduce the problem to the case  $\varphi \equiv 0$ . To do so we observe that we may assume that  $\varphi$  and  $\varphi_x$  belong to  $C(\mathbb{R} \times [0, \infty))$  by setting

$$\varphi(x, t) = \varphi(b, t) + \varphi_x(b, t)(x - b) \text{ for } x \geq b,$$

and

$$\varphi(x, t) = \varphi(a, t) + \varphi_x(a, t)(x - a) \text{ for } x \leq a.$$

We also assume without loss of generality that  $c = 1$ . Taking the difference between the unknown function  $u(x, t)$  and

$$\frac{1}{2} \int \int_{G(x, t)} \varphi(\xi, \tau) d\xi d\tau,$$

and renaming this difference  $u$  again, we obtain a new problem, with new functions  $A, B, \alpha$  and  $\beta$ , and with  $\varphi = 0$ , satisfying the same regularity and compatibility conditions.

We construct a solution for  $0 < t \leq b - a$ . The square  $[a, b] \times [0, b - a]$  is subdivided by its diagonals into four triangles, which we number counterclockwise starting at the bottom as  $I, II, III$  and  $IV$ . To compute  $u$  in  $I$ , we use the formula

$$u(x, t) = \frac{1}{2} \{ \alpha(x + t) + \alpha(x - t) \} + \frac{1}{2} \int_{x-t}^{x+t} \beta(s) ds.$$

We then define  $u$  for every  $(x, t)$  in  $II$  and  $IV$  using the difference equation in Lemma 6.2 for characteristic rectangles with two vertices contained in  $I$ , one on the lateral boundary, and the last one at  $(x, t)$ . Then with  $u$  being determined for every point in  $II$  and  $IV$ , we extend  $u$  to  $III$  using the difference equation again, now applied to characteristic rectangles with one vertex in each triangle. This defines a function  $u$  on  $[a, b] \times [0, b - a]$ .

Repeating the construction on  $[a, b] \times [b - a, 2(b - a)]$ , etc., we obtain the value of  $u(x, t)$  for every  $(x, t)$  in  $(a, b) \times (0, \infty)$ . We claim that  $u \in C^2([a, b] \times [0, \infty))$ , and that  $u_{tt} = u_{xx}$ . Clearly, because of the previous results it suffices to establish  $u \in C^2([a, b] \times [0, \infty))$ . This is left as an exercise. ■

## 7. The fundamental solution in one space dimension

We have seen that under appropriate conditions on  $\alpha, \beta$  and  $\varphi$ , the solution of

$$(CP_i) \begin{cases} u_{tt} - u_{xx} = \varphi(x, t) & x, t \in \mathbb{R}; \\ u(x, 0) = \alpha(x) & x \in \mathbb{R}; \\ u_t(x, 0) = \beta(x) & x \in \mathbb{R}, \end{cases}$$

is given by

$$u(x, t) = u_\alpha(x, t) + u_\beta(x, t) + u_p(x, t), \quad (7.1)$$

where

$$u_\alpha(x, t) = \frac{1}{2} \alpha(x + t) + \frac{1}{2} \alpha(x - t); \quad u_\beta(x, t) = \frac{1}{2} \int_{x-t}^{x+t} \beta(s) ds;$$

$$u_p(x, t) = \frac{1}{2} \int \int_{G(x, t)} \varphi(\xi, \tau) d\xi d\tau; \quad G(x, t) = \{(\xi, \tau), 0 \leq \tau \leq t, |\xi - x| \leq t - \tau\}.$$

Note that  $u_\alpha$  is the solution of  $u_{tt} = u_{xx}$  with  $u(x, 0) = \alpha(x)$  and  $u_t(x, 0) \equiv 0$ ,  $u_\beta$  of  $u_{tt} = u_{xx}$  with  $u(x, 0) \equiv 0$  and  $u_t(x, 0) = \beta(x)$ , and  $u_p$  of  $u_{tt} = u_{xx} + \varphi$  with  $u(x, 0) \equiv u_t(x, 0) \equiv 0$ . In fact these three different functions are constructed by means of one (*fundamental*) solution. To see this we have to make a small detour into the theory of distributions.

As an example we consider first the so-called *Heaviside function*:

$$H(s) = \begin{cases} 0 & s < 0; \\ 1 & s > 0. \end{cases}$$

If we look at  $H$  as an element of  $L^1_{loc}(\mathbb{R})$ ,  $H(0)$  need not be defined. If we look at  $H$  as a “*maximal monotone graph*”, we must set  $H(0) = [0, 1]$ . We cannot differentiate  $H$  in the class of functions, but we can in the class of distributions. The “*testfunctions space*” is defined by

$$D(\mathbb{R}) = \{\psi \in C^\infty(\mathbb{R}); \psi \text{ has compact support}\}.$$

We say that for  $\psi_n, n = 1, 2, \dots$ , and  $\psi$  in  $D(\mathbb{R})$ ,

$$\psi_n \rightarrow \psi \quad \text{as} \quad n \rightarrow \infty \quad \text{in} \quad D(\mathbb{R}),$$

if the supports of  $\psi_n^{(k)}$  are uniformly bounded, and if  $\psi_n^{(k)} \rightarrow \psi^{(k)}$  uniformly on  $\mathbb{R}$  for all  $k = 0, 1, 2, \dots$

**7.1 Definition** A linear functional  $T : D(\mathbb{R}) \rightarrow \mathbb{R}$  is called a distribution if  $\psi_n \rightarrow \psi$  in  $D(\mathbb{R})$  implies that  $T\psi_n \rightarrow T\psi$ .

Every  $\varphi \in L^1_{loc}(\mathbb{R})$  defines a distribution

$$T_\varphi(\psi) = \langle \varphi, \psi \rangle = \int_{-\infty}^{\infty} \varphi \psi. \quad (7.2)$$

Now suppose we take for  $\varphi$  a smooth function. Then

$$T_{\varphi'}(\psi) = \langle \varphi', \psi \rangle = \int_{-\infty}^{\infty} \varphi' \psi = - \int_{-\infty}^{\infty} \varphi \psi' = - \langle \varphi, \psi' \rangle = -T_\varphi(\psi'). \quad (7.3)$$

In view of this property, the following definition is natural.

**7.2 Definition** Let  $T : D(\mathbb{R}) \rightarrow \mathbb{R}$  be a distribution. Define  $T' : D(\mathbb{R}) \rightarrow \mathbb{R}$  by  $T'(\psi) = -T(\psi')$ . Then  $T'$  is called the *distributional derivative* of  $T$ . Note that  $T'$  is again a distribution.

**7.3 Example** Let  $H$  be the Heaviside function. Then

$$T_H(\psi) = \langle H, \psi \rangle = \int_{-\infty}^{\infty} H(s)\psi(s)ds = \int_0^{\infty} \psi(s)ds,$$

and

$$(T_H)'(\psi) = \langle H', \psi \rangle = - \int_{-\infty}^{\infty} H(s)\psi'(s)ds = - \int_0^{\infty} \psi'(s)ds = \psi(0).$$

We introduce the *Dirac delta distribution*  $\delta = \delta(x)$  by

$$\langle \delta, \psi \rangle = \int_{-\infty}^{\infty} \delta(x)\psi(x)dx = \psi(0). \quad (7.4)$$

Clearly  $\delta$  is the distributional derivative of  $H$ . Intuitively,  $\delta$  is a function with

$$\delta(x) = 0 \text{ for } x \neq 0; \delta(0) = +\infty; \int_{-\infty}^{\infty} \delta(x)dx = 1,$$

but one should always remember that mathematically speaking,  $\delta$  is not a function. A better and correct way is to say that  $\delta$  is a measure which assigns the value one to any set containing zero.

Returning to  $u_\beta$  we have that, for  $t \geq 0$

$$\begin{aligned} u_\beta(x, t) &= \frac{1}{2} \int_{x-t}^{x+t} \beta(s)ds = \int_{-\infty}^{\infty} \frac{1}{2} H(x+t-s)H(s-x+t)\beta(s)ds = \\ &= \int_{-\infty}^{\infty} E^+(x-s, t)\beta(s)ds, \end{aligned}$$

where

$$E^+(x, t) = \frac{1}{2} H(t+x)H(t-x), \quad x \in \mathbb{R}, \quad t \geq 0.$$

We extend  $E^+$  to the whole of  $\mathbb{R}^2$  by setting  $E^+(x, t) = 0$  for  $t \leq 0$ . Note that we can also write

$$E^+(x, t) = \frac{1}{2} H(t)\{H(x+t) - H(x-t)\}, \quad (7.5)$$

and that  $\text{supp } E^+ \subset \mathbb{R} \times \bar{\mathbb{R}}^+$ . Extending the definitions of distributions and their derivatives in the obvious way from  $\mathbb{R}$  to  $\mathbb{R}^2$ , and in particular defining the Dirac distribution in  $\mathbb{R} \times \mathbb{R}$  by

$$\langle \delta, \psi \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(x, t)\psi(x, t)dx = \psi(0, 0), \quad (7.6)$$

we claim that

$$E_{tt}^+ - E_{xx}^+ = \delta(x, t) = \delta(x)\delta(t) \quad \text{in } \mathbb{R} \times \mathbb{R}. \quad (7.7)$$

To see this, let  $\psi$  be any smooth function with compact support in  $\mathbb{R} \times \mathbb{R}$ , i.e.  $\psi \in D(\mathbb{R} \times \mathbb{R})$ , and let  $\gamma$  be the boundary of the triangle  $\{(x, t) : -t < x < t, 0 < t < T\}$ , where  $T$  is so large that the support of  $\psi$  is contained in  $\{t < T\}$ . Then

$$\begin{aligned} \langle E_{tt}^+ - E_{xx}^+, \psi \rangle &= \iint E^+(x, t)(\psi_{tt} - \psi_{xx}) dx dt = \\ &= \frac{1}{2} \iint_{-t \leq x \leq t} (\psi_{tt} - \psi_{xx}) dx dt = \frac{1}{2} \iint_{-t \leq x \leq t} \frac{\partial}{\partial x}(-\psi_x) + \frac{\partial}{\partial t}(\psi_t) dx dt \\ &= \frac{1}{2} \iint_{-t \leq x \leq t} \operatorname{div} \begin{pmatrix} -\psi_x \\ \psi_t \end{pmatrix} dx dt = \frac{1}{2} \oint_{\gamma} \begin{pmatrix} -\psi_x \\ \psi_t \end{pmatrix} \cdot \nu ds = \\ &= -\frac{1}{2} \oint_{\gamma} \psi_x dt + \psi_t dx = \psi(0, 0) = \langle \delta, \psi \rangle. \end{aligned}$$

Next we compute, as distributions on  $\mathbb{R}$ , for  $t > 0$ ,

$$\langle E^+(\cdot, t), \psi \rangle = \int_{-\infty}^{\infty} E^+(x, t) \psi(x) dx = \int_{-t}^t \psi(x) dx,$$

for all  $\psi \in D(\mathbb{R})$ . Clearly,  $\langle E^+(\cdot, t), \psi \rangle \rightarrow 0$  as  $t \downarrow 0$ . In view of the following definition we say that  $E^+(\cdot, t) \rightarrow 0$  as  $t \downarrow 0$  in the class of distributions on  $\mathbb{R}$ .

**7.4 Definition** Let  $T_n, n = 1, 2, \dots$ , and  $T$  be distributions on an open set  $\Omega \subset \mathbb{R}^n$ . We say that  $T_n \rightarrow T$  if  $T_n \psi \rightarrow T \psi$  for all  $\psi \in D(\Omega)$ .

Finally we look at  $E_t^+$ . Again let  $\psi \in D(\mathbb{R} \times \mathbb{R})$ . Then

$$\begin{aligned} \langle E_t^+, \psi \rangle &= - \langle E^+, \psi_t \rangle = -\frac{1}{2} \iint_{-t \leq x \leq t} \psi_t(x, t) dx dt = \\ &= \frac{1}{2} \int_0^{\infty} \psi(x, x) dx + \frac{1}{2} \int_{-\infty}^0 \psi(x, -x) dx = \frac{1}{2} \int_0^{\infty} (\psi(t, t) + \psi(-t, t)) dt \\ &= \int_0^{\infty} \langle \frac{1}{2}(\delta(x-t) + \delta(x+t)), \psi(x, t) \rangle dt. \end{aligned}$$

Here we have used the notation

$$\langle \delta(\cdot \pm t), \psi \rangle = \int \delta(x \pm t) \psi(x) dx = \psi(\mp t).$$

Symbolically we write for  $t > 0$ ,

$$E_t^+(x, t) = \frac{1}{2}\delta(x + t) + \frac{1}{2}\delta(x - t). \quad (7.8)$$

Consequently, for  $\psi \in D(\mathbb{R})$ ,

$$\langle E_t^+(\cdot, t), \psi \rangle = \frac{1}{2}\psi(-t) + \frac{1}{2}\psi(t) \rightarrow \psi(0) = \langle \delta(x), \psi(x) \rangle$$

as  $t \downarrow 0$ , i.e.  $E_t^+(\cdot, t) \rightarrow \delta$  as  $t \downarrow 0$ .

**7.5 Definition**  $E^+$  is called the *fundamental solution* of  $u_{tt} = u_{xx}$ . Its support, the set  $\{|x| \leq t\}$  is called the *forward light cone*.

**7.6 Remark** The derivation of the formula above for  $E_t^+$  is formal, but can be made mathematically rigorous, if one considers  $\delta$  as a measure.

**7.7 Definition** For  $f, g : \mathbb{R} \rightarrow \mathbb{R}$  the convolution of  $f$  and  $g$  is given by

$$(f * g)(x) = \int_{-\infty}^{\infty} f(x - s)g(s)ds,$$

whenever this integral exists.

Now recall that for  $t > 0$

$$u_\beta(x, t) = \int_{-\infty}^{\infty} E^+(x - s, t)\beta(s)ds, \quad (7.9)$$

i.e.  $u_\beta(\cdot, t)$  is the convolution of  $E^+(\cdot, t)$  and  $\beta$ .

Next we consider  $u_\alpha$ . For  $t > 0$  we have

$$\begin{aligned} u_\alpha(x, t) &= \frac{1}{2}\alpha(x + t) + \frac{1}{2}\alpha(x - t) = \int_{-\infty}^{\infty} \frac{1}{2}(\delta(x - s + t) + \delta(x - s - t))\alpha(s)ds \\ &= \int_{-\infty}^{\infty} E_t^+(x - s, t)\alpha(s)ds, \end{aligned}$$

so that formally  $u_\alpha$  is the convolution of  $E_t^+(\cdot, t)$  and  $\alpha$ .

Finally we look at  $u_p$ . We have for  $t > 0$

$$u_p(x, t) = \frac{1}{2} \int \int_{G(x, t)} \psi(\xi, \tau) d\xi d\tau = \frac{1}{2} \int_0^t \int_{x-t+\tau}^{x+t-\tau} \psi(\xi, \tau) d\xi d\tau$$



$$\begin{aligned}
&= \frac{1}{2} \int_0^t \int_{-\infty}^{\infty} H(\xi - x + t - \tau) H(x + t - \tau - \xi) \psi(\xi, \tau) d\xi d\tau \\
&= \int_0^t \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \psi(\xi, \tau) d\xi d\tau.
\end{aligned}$$

Now this is the convolution of  $E^+$  and  $\psi$  with respect to both variables in  $\mathbb{R} \times \mathbb{R}^+$ . Summarizing we have for  $t > 0$

$$u_\alpha = E_t^+(\cdot, t) * \alpha \quad \text{and} \quad u_\beta = E^+(\cdot, t) * \beta \quad (\text{convolution in } x);$$

$$u_p = E^+ * \varphi \quad (\text{convolution in } x \text{ and } t).$$

## 8. The fundamental solution in three and two space dimensions

For the wave equation in one dimension, we have constructed the fundamental solution

$$E^+(x, t) = \frac{1}{2} H(t) \{H(x + t) - H(x - t)\},$$

which was a distributional solution on  $\mathbb{R} \times \mathbb{R}$  of  $u_{tt} - u_{xx} = \delta(x, t) = \delta(x)\delta(t)$ , with support contained in  $\mathbb{R} \times [0, \infty)$ .

Next we turn to the 3-dimensional case and try to find the analog of  $E^+$ . Thus we try to find a distribution in  $\mathbb{R}^3 \times \mathbb{R}$  with support contained in  $\{t \geq 0\}$ , satisfying

$$u_{tt} - \Delta u = \delta(x_1, x_2, x_3, t) = \delta(x_1)\delta(x_2)\delta(x_3)\delta(t). \quad (8.1)$$

We shall first obtain a solution by formal methods, and then give a rigorous proof.

Because of the radial symmetry in this problem, we look for a solution of the form  $u = u(r, t)$ . For  $t > 0$  this implies

$$u_{tt} = u_{rr} + \frac{2}{r}u_r,$$

or (this trick only works for  $N = 3$ )

$$(ru)_{tt} = (ru)_{rr}.$$

As in the one dimensional case we conclude that

$$ru(r, t) = v(t - r) + w(t + r).$$

Because the second term reflects signals coming inwards, we neglect it. Thus we consider

$$u(r, t) = \frac{v(t - r)}{r}.$$

Tracing “characteristics” of the form  $t - r = c$  backwards in time, we conclude that  $v(c) = 0$  if  $c \neq 0$ . These considerations suggest that  $v(t - r) = \delta(t - r)$  (up to a constant).

**8.1 Theorem** The fundamental solution of the wave equation in  $\mathbb{R}^3 \times \mathbb{R}$ , i.e. the solution of (8.1) with support in  $\mathbb{R}^3 \times [0, \infty]$ , is given by

$$E^+(x_1, x_2, x_3, t) = \frac{\delta(t - r)}{4\pi r},$$

which we define as a distribution below.

In order to define  $E^+$  as a distribution, we first compute formally what  $\langle E^+, \psi \rangle$  would be for  $\psi \in D(\mathbb{R}^3 \times \mathbb{R})$ , using the “rule”

$$\int \varphi(s) \delta(t - s) ds = \varphi(t).$$

Thus we evaluate  $\langle E^+, \psi \rangle$  using polar coordinates

$$x_1 = r \sin \theta \cos \varphi; \quad x_2 = r \sin \theta \sin \varphi; \quad x_3 = r \cos \theta.$$

Then

$$\begin{aligned} \langle E^+, \psi \rangle &= \int_{-\infty}^{\infty} \int_0^{\pi} \int_0^{2\pi} \int_0^{\infty} \frac{\delta(t - r)}{4\pi r} \psi(r \sin \theta \cos \varphi, r \sin \theta \sin \varphi, r \cos \theta, t) r^2 \sin \theta \, dr d\varphi d\theta dt \\ &= \int_0^{\infty} \int_0^{\pi} \int_0^{2\pi} \frac{1}{4\pi t} \psi(t \sin \theta \cos \varphi, t \sin \theta \sin \varphi, t \cos \theta, t) t^2 \sin \theta d\varphi d\theta dt = \\ &\quad \int_0^{\infty} \frac{1}{4\pi t} \oint_{x_1^2 + x_2^2 + x_3^2 = t^2} \psi(x_1, x_2, x_3, t) \, dS \, dt, \end{aligned}$$

and we use this final expression as a definition of  $E^+$ .

**8.2 Definition** We define the distribution  $E^+$  on  $\mathbb{R}^3 \times \mathbb{R}$  by

$$\langle E^+, \psi \rangle = \int_0^{\infty} \frac{1}{4\pi t} \oint_{x_1^2 + x_2^2 + x_3^2 = t^2} \psi(x_1, x_2, x_3, t) \, dS(x_1, x_2, x_3) \, dt$$

for all  $\psi \in D(\mathbb{R}^3 \times \mathbb{R})$ . We also define  $E^+(\cdot, \cdot, \cdot, t)$  as a distribution on  $\mathbb{R}^3$  by

$$\langle E^+(t), \psi \rangle = \frac{1}{4\pi t} \oint_{x_1^2 + x_2^2 + x_3^2 = t^2} \psi(x_1, x_2, x_3) \, dS(x_1, x_2, x_3).$$

Next we prove that  $E^+$  is a fundamental solution.

**8.3 Lemma**  $E^+$  satisfies  $E_{tt}^+ - \Delta E^+ = \delta(x_1, x_2, x_3, t)$  in  $\mathbb{R}^3 \times \mathbb{R}$ .

**Proof** Let  $\psi \in D(\mathbb{R}^3 \times \mathbb{R})$ . Since  $\langle \delta(x_1, x_2, x_3, t), \psi(x_1, x_2, x_3, t) \rangle = \psi(0, 0, 0, 0)$ , and  $\langle E_{tt}^+ - \Delta E^+, \psi \rangle = \langle E^+, \psi_{tt} - \Delta \psi \rangle$ , we have to show that  $\langle E^+, \psi_{tt} - \Delta \psi \rangle = \psi(0, 0, 0, 0)$ . Again we use polar coordinates. We have

$$\Delta \psi = \frac{1}{r^2} (r^2 \psi_r)_r + \frac{1}{r^2 \sin \theta} (\sin \theta \psi_\theta)_\theta + \frac{1}{r^2 \sin^2 \theta} \psi_{\varphi\varphi},$$

so that

$$\begin{aligned} \langle E^+, \psi_{tt} - \Delta \psi \rangle &= \\ \int_0^\infty \int_0^\pi \int_0^{2\pi} \frac{1}{4\pi t} \left[ \psi_{tt} - \frac{1}{r^2} \{ (r^2 \psi_r)_r - \frac{1}{\sin \theta} (\sin \theta \psi_\theta)_\theta - \frac{1}{\sin^2 \theta} \psi_{\varphi\varphi} \} \right]_{r=t} t^2 \sin \theta d\varphi d\theta dt \\ &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \frac{1}{4\pi} [(r\psi)_{tt} - (r\psi)_{rr}]_{r=t} \sin \theta d\varphi d\theta dt \\ &\quad - \int_0^\infty \int_0^\pi \int_0^{2\pi} (\sin \theta \psi_\theta)_\theta d\varphi d\theta dt - \int_0^\infty \int_0^\pi \int_0^{2\pi} \frac{\psi_{\varphi\varphi}}{\sin \theta} d\varphi d\theta dt. \end{aligned}$$

Obviously, the last two integrals are zero, so if  $\gamma$  is the curve  $\{r = t > 0\}$  in the  $(r, t)$ - plane (along which we have  $dr = dt$ ), then

$$\begin{aligned} \langle E_{tt}^+ - \Delta E^+, \psi \rangle &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \frac{1}{4\pi} [(r\psi)_{tt} - (r\psi)_{rr}]_{r=t} \sin \theta d\varphi d\theta dt = \\ &\quad \frac{1}{4\pi} \int_0^\pi \int_0^{2\pi} \sin \theta \int_\gamma \{ (r\psi)_{tt} - (r\psi)_{rr} \} dt d\varphi d\theta = \\ &\quad \frac{1}{4\pi} \int_0^\pi \int_0^{2\pi} \sin \theta \int_\gamma \{ (r\psi)_{tt} dt + (r\psi)_{tr} dr - (r\psi)_{rr} dr - (r\psi)_{rt} dt \} d\varphi d\theta = \end{aligned}$$

(since  $\psi$  has compact support)

$$\frac{1}{4\pi} \int_0^\pi \int_0^{2\pi} \sin \theta [(r\psi)_r - (r\psi)_t]_{r=t=0} d\varphi d\theta = \psi(0, 0, 0, 0).$$

This completes the proof. ■

Formally now, the solution of the equation  $u_{tt} - \Delta u = \varphi(x_1, x_2, x_3, t)$  in  $\mathbb{R} \times [0, \infty]$  with  $u = u_t \equiv 0$  for  $t < 0$ , should be obtained by taking the convolution of  $E^+$  and  $\varphi$  with respect to all variables, just like in the one-dimensional case. However, here  $E^+$  is no longer a function, so the definition of this convolution is not entirely

obvious. We shall restrict ourselves here to the formal computation. Then, with  $(x, y, z) = (x_1, x_2, x_3)$ , we have for  $t > 0$ ,

$$u(x, y, z, t) = \int_0^t \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E(x - \xi, y - \eta, z - \zeta, t - \tau) \varphi(\xi, \eta, \zeta, \tau) d\xi d\eta d\zeta d\tau =$$

(writing  $P = (x, y, z)$ ,  $Q = (\xi, \eta, \zeta)$ , and  $r_{PQ} = \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2}$ )

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_0^t \frac{\delta(t - r - r_{PQ})}{4\pi r_{PQ}} \varphi(\xi, \eta, \zeta, \tau) d\tau d\xi d\eta d\zeta =$$

(using the "rule"  $\int \varphi(\tau) \delta(s - t) ds = \varphi(t)$ )

$$\frac{1}{4\pi} \int \int \int_{r_{PQ} \leq t} \frac{\varphi(\xi, \eta, \zeta, t - r_{PQ})}{r_{PQ}} d\xi d\eta d\zeta =$$

$$\int \int \int_{G(x, y, z, t)} \frac{\varphi(\xi, \eta, \zeta, t - \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2})}{4\pi \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2}} d\xi d\eta d\zeta,$$

where

$$G(x, y, z, t) = \{(\xi, \eta, \zeta, \tau) : (x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2 \leq t^2\}.$$

Next we treat (only formally) some special cases.

**8.4 Example** Consider

$$\varphi(x, y, z, t) = \delta(x)\delta(y)\delta(z)f(t).$$

We find that  $u(x, y, z, t) =$

$$\begin{aligned} \int \int \int_{G(x, y, z, t)} \frac{\delta(\xi)\delta(\eta)\delta(\zeta)f(t - \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2})}{4\pi \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2}} d\xi d\eta d\zeta \\ = \frac{f(t - r)}{4\pi r}. \end{aligned}$$

**8.5 Example** Consider  $\varphi(x, y, z, t) = \delta(x)\delta(y)f(t)$ . Then  $u(x, y, z, t) =$

$$\begin{aligned} \int \int \int_{G(x, y, z, t)} \frac{\delta(\xi)\delta(\eta)f(t - \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2})}{4\pi \sqrt{(x - \xi)^2 + (y - \eta)^2 + (z - \zeta)^2}} d\xi d\eta d\zeta \\ = \frac{1}{2\pi} \int_{x^2 + y^2 + (z - \zeta)^2 \leq t^2, z - \zeta \geq 0} \frac{f(t - \sqrt{x^2 + y^2 + (z - \zeta)^2})}{\sqrt{x^2 + y^2 + (z - \zeta)^2}} d\zeta \end{aligned}$$

$$= \frac{1}{2\pi} \int_0^{t-r} \frac{f(\tau) d\tau}{\sqrt{(t-\tau)^2 - r^2}}.$$

(here  $r = \sqrt{x^2 + y^2}$ ,  $\tau = t - \sqrt{x^2 + y^2 + (z - \zeta)^2}$ ,  $d\tau = \frac{-\zeta + z}{\sqrt{x^2 + y^2 + (z - \zeta)^2}} d\zeta$ ,  $(z - \zeta)^2 = (t - \tau)^2 - r^2$ )

**8.6 Example** Consider  $\varphi(x, y, z, t) = \delta(x)\delta(y)\delta(t)$  (or  $f(t) = \delta(t)$  in the last example), then

$$u(x, y, z, t) = \frac{1}{2\pi} \int_0^{t-r} \frac{\delta(\tau)}{\sqrt{(t-\tau)^2 - r^2}} dt = \frac{1}{2\pi} \frac{H(t-r)}{\sqrt{t^2 - r^2}}$$

Note however that this last expression is independent of  $t$ , so we have found the fundamental solution for the wave equation in two dimensions.

**8.7 Proposition** Let  $E^+(x, y, t)$  be given by

$$E^+(x, y, t) = \frac{1}{2\pi} \frac{H(t-r)}{\sqrt{t^2 - r^2}}$$

Then  $E^+$  is the fundamental solution of the wave equation in two dimensions, i.e.  $E^+$  has support in  $\{t \geq 0\}$  and satisfies  $E_{tt}^+ - E_{xx}^+ - E_{yy}^+ = \delta(x, y, t) = \delta(x, y, t)$  on  $\mathbb{R}^2 \times \mathbb{R}$  in the sense of distributions.

**Proof** First note that  $E^+$  is now a function. We have to show that  $\langle E_{tt}^+ - E_{xx}^+ - E_{yy}^+, \psi \rangle = \langle E^+, \psi_{tt} - \psi_{xx} - \psi_{yy} \rangle = \psi(0, 0, 0)$  for all  $\psi \in D(\mathbb{R}^2 \times \mathbb{R})$ . To do so we introduce polar coordinates on  $\mathbb{R}^2$ ,  $x = r \cos \varphi$ ;  $y = r \sin \varphi$ . Then

$$\Delta \psi = \psi_{xx} + \psi_{yy} = \frac{1}{r} (r\psi_r)_r + \frac{1}{r^2} \psi_{\varphi\varphi}.$$

Thus

$$\begin{aligned} \langle E^+, \psi_{tt} - \Delta \psi \rangle &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{1}{2\pi} \frac{H(t-r)}{\sqrt{t^2 - r^2}} (\psi_{tt} - \Delta \psi) dx dy dt \\ &= \int_0^{\infty} \int_0^{2\pi} \int_0^t \frac{\psi_{tt} - r^{-1}(r\psi_r)_r - r^{-2}\psi_{\varphi\varphi}}{2\pi\sqrt{t^2 - r^2}} r dr d\varphi dt \\ &= \int_0^{\infty} \int_0^{2\pi} \int_0^t \frac{r\psi_{tt} - (t\psi_r)_r}{2\pi\sqrt{t^2 - r^2}} dr d\varphi dt = \frac{1}{2\pi} \int_0^{2\pi} J(\varphi) d\varphi, \end{aligned}$$

where

$$J(\varphi) = \int_0^{\infty} \int_0^t \frac{r\psi_{tt} - (r\psi_r)_r}{\sqrt{t^2 - r^2}} dr dt =$$

(if  $\text{supp}\psi \subset \{t \leq T\}$ )

$$\int_0^T \int_0^t \frac{r\psi_{rr} - (r\psi_r)_r}{\sqrt{t^2 - r^2}} dr dt = \lim_{\varepsilon \downarrow 0} \int_\varepsilon^T \int_\varepsilon^t \frac{r\psi_{rr} - (r\psi_r)_r}{\sqrt{t^2 - r^2}} dr dt =$$

(using the transformation  $x = r$ ,  $y = t/r$ )

$$\lim_{\varepsilon \downarrow 0} \int_\varepsilon^T \int_1^{T/x} \left\{ \frac{-(\psi_y \sqrt{y^2 - 1})_y}{x} - \frac{(x\psi_x)_x}{\sqrt{y^2 - 1}} + \frac{2y\psi_{xy}}{\sqrt{y^2 - 1}} \right\} dy dx$$

(here we have used

$$\frac{\partial}{\partial r} = \frac{\partial}{\partial x} - \frac{y}{x} \frac{\partial}{\partial y} \quad \text{and} \quad \frac{\partial}{\partial t} = \frac{1}{x} \frac{\partial}{\partial y},$$

to transform the derivatives, and  $drdt = xdx dy$ )

$$\begin{aligned} &= \lim_{\varepsilon \downarrow 0} \left\{ \int_\varepsilon^T \left[ -\frac{\psi_y \sqrt{y^2 - 1}}{x} \right]_{y=1}^{y=T/x} dx + \int_1^{T/\varepsilon} \left[ \frac{2y\psi_y - x\psi_x}{\sqrt{y^2 - 1}} \right]_{x=\varepsilon}^{x=T/y} dy \right\} \\ &= \lim_{\varepsilon \downarrow 0} \int_1^{T/\varepsilon} \frac{x\psi_x - 2y\psi_y}{\sqrt{y^2 - 1}} \Big|_{x=\varepsilon} dy = \end{aligned}$$

(transforming the  $x$ - and  $y$ -derivatives back to  $r$ - and  $t$ -derivatives)

$$\lim_{\varepsilon \downarrow 0} \int_1^{T/\varepsilon} \frac{\varepsilon\psi_r - \varepsilon y\psi_t}{\sqrt{y^2 - 1}} \Big|_{x=\varepsilon} dy =$$

(writing  $\psi(r, \varphi, t)$ )

$$\lim_{\varepsilon \downarrow 0} \int_1^{T/\varepsilon} \frac{\varepsilon\psi_r(\varepsilon, \varphi, \varepsilon y) - \varepsilon y\psi_t(\varepsilon, \varphi, t)}{\sqrt{y^2 - 1}} dy =$$

(substituting  $t = \varepsilon y$ )

$$\begin{aligned} &\lim_{\varepsilon \downarrow 0} \int_\varepsilon^T \frac{\varepsilon\psi_r(\varepsilon, \varphi, t) - t\psi_t(\varepsilon, \varphi, t)}{\sqrt{t^2 - \varepsilon^2}} dt = \\ &\lim_{\varepsilon \downarrow 0} \int_0^{T-\varepsilon} \left\{ \frac{\varepsilon\psi_r(\varepsilon, \varphi, t+\varepsilon)}{\sqrt{(t+2\varepsilon)t}} - \frac{t+\varepsilon}{\sqrt{(t+2\varepsilon)t}} \psi_t(\varepsilon, \varphi, t+\varepsilon) \right\} dt \\ &= - \int_0^T \psi_t(0, \varphi, t) dt = \psi(0, \varphi, 0), \end{aligned}$$

which completes the proof. ■

## PART 3: THE HEAT EQUATION

### 9. The fundamental solution of the heat equation in dimension one

As a first example we consider the problem

$$(P) \begin{cases} u_t = u_{xx} & x \in \mathbb{R}, t > 0; \\ u(x, 0) = H(x) & x \in \mathbb{R}, \end{cases}$$

where  $H$  is the Heaviside function. Now observe that if  $u(x, t)$  is a solution of (P), then  $u_a(x, t) = u(ax, a^2t)$  is also a solution of (P). Since we expect the solution to be unique, we should have

$$u(ax, a^2t) = u(x, t), \quad (9.1)$$

for all  $a > 0$ ,  $x \in \mathbb{R}$ ,  $t > 0$ . Thus if we put  $a = 1/\sqrt{t}$ , we obtain

$$u(x, t) = u\left(\frac{x}{\sqrt{t}}, 1\right) = U(\eta); \quad \eta = \frac{x}{\sqrt{t}}. \quad (9.2)$$

Here  $\eta$  is called the *similarity variable*. From (9.2) it follows that

$$u_t = U'(\eta) \frac{\partial \eta}{\partial t} = U'(\eta) \frac{x}{2t\sqrt{t}} = -\frac{\eta U'(\eta)}{2t}; \quad u_{xx} = \frac{U''}{t},$$

so that  $u(x, t) = U(\eta)$  is a solution of the heat equation if

$$U''(\eta) + \eta U'(\eta)/2 = 0, \quad (9.3)$$

or

$$(e^{\eta^2/4} U'(\eta))' = 0.$$

Thus

$$e^{\eta^2/4} U'(\eta) = \text{constant} = A,$$

and

$$U(\eta) = B + A \int_{-\infty}^{\eta} e^{-s^2/4} ds = B + 2A \int_{-\infty}^{\eta/2} e^{-y^2} dy.$$

Since for  $x < 0$ ,

$$0 = u(x, 0) = \lim_{t \downarrow 0} U\left(\frac{x}{\sqrt{t}}\right) = U(-\infty) = B,$$

and for  $x > 0$ ,

$$1 = u(x, 0) = \lim_{t \downarrow 0} U\left(\frac{x}{\sqrt{t}}\right) = U(+\infty) = B + 2A \int_{-\infty}^{\infty} e^{-\eta^2} d\eta = 2A\sqrt{\pi},$$

we find that

$$U(\eta) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{\eta/2} e^{-s^2} ds; u(x, t) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{x/2\sqrt{t}} e^{-s^2} ds. \quad (9.4)$$

We make the following observations.

(i)  $u(x, t)$  is *smooth* for  $t > 0$ , but not at  $t = 0$ ,

$$(ii) \lim_{t \downarrow 0} u(x, t) = \begin{cases} 0 & x < 0 \\ 1/2 & x = 0, \\ 1 & x > 0 \end{cases}$$

(iii)  $0 = \min_{x \in \mathbb{R}} u(x, 0) < u(x, t) < \max_{x \in \mathbb{R}} u(x, 0) = 1$  (i.e a *strong comparison principle* seems to hold),

(iv) The positivity of  $u$  on  $\mathbb{R}^+$  for  $t = 0$  causes  $u$  to become positive immediately for  $t > 0$  on the whole of  $\mathbb{R}$  (*infinite speed of propagation*, in sharp contrast with the finite speed of propagation for the wave equation),

(v)  $u(x, t) = U(x/\sqrt{t})$  is a self similar solution (or *similarity solution*).

Next we compute the solution of the heat equation with the initial value

$$u(x, 0) = \begin{cases} 0 & x < a \\ 1 & x > a \end{cases}.$$

Naturally we obtain

$$u_a(x, t) = \frac{1}{\sqrt{\pi}} \int_{-\infty}^{(x-a)/2\sqrt{t}} e^{-s^2} ds,$$

so that the solution with initial conditions

$$w(x, 0) = \begin{cases} 0 & x < 0 \\ 1 & 0 < x < a \\ 0 & x > a \end{cases},$$

is given by

$$w(x, t) = u(x, t) - u_a(x, t) = \frac{1}{\sqrt{\pi}} \int_{(x-a)/2\sqrt{t}}^{x/2\sqrt{t}} e^{-s^2} ds,$$

which obviously satisfies

$$|w(x, t)| = |u(x, t) - u_a(x, t)| < \frac{a}{2\sqrt{\pi t}}.$$



Thus  $w(x, t) \rightarrow 0$  as  $t \rightarrow \infty$ , the decay order being  $1/\sqrt{t}$ . Note that  $w(x, 0)$  is a bounded integrable function.

Going back to the solution with  $u(x, 0) = H(x)$ , which is given by (9.4), we differentiate it with respect to  $t$ , to obtain a new solution

$$E^+(x, t) = \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t}. \quad (9.5)$$

Obviously  $E^+$  satisfies  $E_t^+ = E_{xx}^+$  for  $t > 0$ , and it is in fact the *fundamental solution for the heat equation*, that is, extending  $E^+$  by  $E^+(x, t) = 0$  for  $t < 0$ , we have

**9.1 Proposition** The function  $E^+$  satisfies the fundamental equation  $E_t^+ - E_{xx}^+ = \delta(x, t) = \delta(x)\delta(t)$  in  $\mathbb{R}^2$ .

**Proof** To check that  $E^+$  is indeed a fundamental solution, we let  $\psi \in D(\mathbb{R} \times \mathbb{R})$  and compute

$$\begin{aligned} \langle E_t^+ - E_{xx}^+, \psi \rangle &= - \langle E^+, \psi_t + \psi_{xx} \rangle = - \int_{\mathbb{R} \times \mathbb{R}^+} E^+(\psi_t + \psi_{xx}) dx dt = \\ &= - \lim_{\varepsilon \downarrow 0} \int_{\mathbb{R} \times (\varepsilon, \infty)} E^+(\psi_t + \psi_{xx}) dx dt = \\ &= - \lim_{\varepsilon \downarrow 0} \left\{ \int_{-\infty}^{\infty} \int_{\varepsilon}^{\infty} E^+ \psi_t dt dx + \int_{\varepsilon}^{\infty} \int_{-\infty}^{\infty} E^+ \psi_{xx} dx dt \right\} = \\ &= - \lim_{\varepsilon \downarrow 0} \left\{ \int_{-\infty}^{\infty} [E^+ \psi]_{t=\varepsilon}^{t=\infty} dx - \int_{-\infty}^{\infty} \int_{\varepsilon}^{\infty} E_t^+ \psi dt dx + \int_{\varepsilon}^{\infty} \int_{-\infty}^{\infty} E_{xx}^+ \psi dx dt \right\} = \\ &= \lim_{\varepsilon \downarrow 0} \int_{-\infty}^{\infty} E^+(x, \varepsilon) \psi(x, \varepsilon) dx = \lim_{t \downarrow 0} \int_{-\infty}^{\infty} \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t} \psi(x, t) dx. \end{aligned}$$

To complete the proof we have to show that this limit equals  $\psi(0, 0)$ .

For all  $\varepsilon > 0$  there exists  $\delta > 0$  such that if  $|x| < \delta$  and  $t < \delta$  then  $|\psi(x, t) - \psi(0, 0)| < \varepsilon$ . Thus

$$\begin{aligned} \left| \int_{-\infty}^{\infty} \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t} \psi(x, t) dx - \psi(0, 0) \right| &= \left| \int_{-\infty}^{\infty} \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t} (\psi(x, t) - \psi(0, 0)) dx \right| \\ &\leq \varepsilon \int_{-\delta}^{\delta} \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t} dx + 2 \sup |\psi| \int_{|x| \geq \delta} \frac{1}{2\sqrt{\pi t}} e^{-x^2/4t} dx \leq \\ &= \varepsilon + \frac{\sup |\psi|}{\sqrt{\pi}} \int_{|s| \geq \delta/\sqrt{t}} e^{-s^2/4} ds \rightarrow \varepsilon \quad \text{as } t \downarrow 0. \end{aligned}$$

Since  $\varepsilon > 0$  was arbitrary this completes the proof. ■

## 10. The Cauchy problem in one dimension

For a given function  $u_0 : \mathbb{R} \rightarrow \mathbb{R}$  we consider the problem

$$(CP) \begin{cases} u_t = u_{xx} & x \in \mathbb{R}, t > 0; \\ u(x, 0) = u_0(x) & x \in \mathbb{R}, \end{cases}$$

Our experience with the wave equation suggests to consider the convolution

$$\begin{aligned} u(x, t) &= (E^+(t) * u_0)(x) = \int_{-\infty}^{\infty} E^+(x - \xi, t) u_0(\xi) d\xi \\ &= \int_{-\infty}^{\infty} \frac{1}{2\sqrt{\pi t}} e^{-(x-\xi)^2/4t} u_0(\xi) d\xi. \end{aligned} \quad (10.1)$$

**10.1 Notation** Let  $Q = \mathbb{R} \times \mathbb{R}^+$ . Then

$$C^{2,1}(Q) = \{u : Q \rightarrow \mathbb{R}; u, u_t, u_x, u_{xx} \in C(Q)\}.$$

**10.2 Theorem** Suppose  $u_0 \in C(\mathbb{R})$  is bounded. Then (CP) has a unique bounded classical solution  $u \in C^{2,1}(Q) \cap C(\overline{Q})$ , given by the convolution (10.1).

**Proof of existence** Clearly  $E^+(\cdot, t) * u_0$  is well defined and bounded for all  $(x, t) \in Q$ , because  $u_0$  is bounded and  $E^+(x, t)$  decays exponentially fast to zero as  $|x| \rightarrow \infty$ . Since the same holds for all partial derivatives of  $E^+(x, t)$ , we can differentiate under the integral with respect to  $x$  and  $t$ . Thus for any  $n, l \in \mathbb{N} \cup \{0\}$ ,

$$\begin{aligned} \left(\frac{\partial}{\partial t}\right)^n \left(\frac{\partial}{\partial x}\right)^l u(x, t) &= \left(\frac{\partial}{\partial t}\right)^n \left(\frac{\partial}{\partial x}\right)^l \int_{-\infty}^{\infty} E^+(x - \xi, t) u_0(\xi) d\xi \\ &= \int_{-\infty}^{\infty} \frac{\partial^{n+l} E^+(x - \xi, t)}{\partial t^n \partial x^l} u_0(\xi) d\xi = \left(\frac{\partial^{n+l} E^+}{\partial t^n \partial x^l}(\cdot, t) * u_0\right)(x), \end{aligned}$$

and in particular

$$\frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = \left(\frac{\partial E^+}{\partial t} - \frac{\partial^2 E^+}{\partial x^2}\right) * u_0 = 0.$$

Hence  $u \in C^\infty(Q)$  satisfies  $u_t = u_{xx}$  in  $Q$ .

It remains to show that for every  $x_0 \in \mathbb{R}$

$$\lim_{\substack{x \rightarrow x_0 \\ t \downarrow 0}} u(x, t) = u_0(x).$$

The argument is similar to the proof that  $E^+$  satisfies the fundamental equation.

Fix  $\varepsilon > 0$ . Then there exists  $\delta > 0$  such that  $|u_0(x) - u_0(x_0)| < \varepsilon$  for  $|x - x_0| < \delta$ . For  $|x - x_0| < \frac{1}{2}\delta$  we have

$$\begin{aligned} |u(x, t) - u_0(x_0)| &= \left| \int_{-\infty}^{\infty} E^+(x - \xi, t)(u_0(\xi) - u_0(x_0))d\xi \right| \leq \\ &\int_{|x - \xi| < \frac{1}{2}\delta} E^+(x - \xi, t)|u_0(\xi) - u_0(x_0)|d\xi + \int_{|x - \xi| > \frac{1}{2}\delta} E^+(x - \xi, t)|u_0(\xi) - u_0(x_0)|d\xi \\ &(\text{since } |x - \xi| < \frac{1}{2}\delta \text{ together with } |x - x_0| < \frac{1}{2}\delta \text{ implies } |\xi - x_0| < \delta) \\ &\leq \varepsilon \int_{|x - \xi| < \frac{1}{2}\delta} E^+(x - \xi, t)d\xi + 2 \sup |u_0| \int_{|x - \xi| > \frac{1}{2}\delta} E^+(x - \xi, t)d\xi \\ &\leq \varepsilon + 2 \sup |u_0| \int_{|\xi| > \frac{1}{2}\delta} E^+(\xi, t)d\xi \rightarrow \varepsilon \text{ as } t \downarrow 0 \end{aligned}$$

as before. Since  $\varepsilon > 0$  was arbitrary, this completes the proof of the existence of a solution. Note that for the continuity of  $u(x, t)$  at  $(x, t) = (x_0, 0)$  we have only used the continuity of  $u_0(x)$  at  $x = x_0$ . ■

**Proof of uniqueness** Suppose there exist two different solutions of (CP) in  $C^{2,1}(Q) \cap C(\overline{Q})$ . Then the difference is a nontrivial classical solution  $u$  of

$$\begin{cases} u_t = u_{xx} & x \in \mathbb{R}, t > 0; \\ u(x, 0) = 0 & x \in \mathbb{R}. \end{cases}$$

This is impossible in view of a *maximum principle* which we state and prove below.

**10.3 Lemma** Suppose  $u \in C^{2,1}(Q_T) \cap C(\overline{Q}_T)$ , where  $Q_T = \mathbb{R} \times (0, T]$  ( $T > 0$ ), satisfies

$$u_t \leq u_{xx} \text{ in } Q_T.$$

If (i)  $u(x, 0) \leq 0$  for all  $x \in \mathbb{R}$ ;

(ii)  $u(x, t) \leq Ae^{Bx^2}$  for all  $(x, t) \in Q_T$ ,

where  $A > 0$  and  $B$  are fixed constants, then

$$u \leq 0 \text{ in } \overline{Q}_T.$$

**10.4 Lemma** For  $-\infty < a < b < \infty$  and  $T > 0$  let  $Q_T^{a,b} = (a, b) \times (0, T]$ , and  $\Gamma_T^{a,b} = \overline{Q}_T^{a,b} \setminus Q_T^{a,b}$ .  $\Gamma_T^{a,b}$  is called the *parabolic boundary* of  $Q_T^{a,b}$ . Suppose  $u \in C^{2,1}(Q_T^{a,b}) \cap C(\overline{Q}_T^{a,b})$  satisfies

$$u_t \leq u_{xx} \text{ in } Q_T^{a,b}.$$

Then

$$\sup_{Q_T^{a,b}} u = \max_{\Gamma_T^{a,b}} u.$$

**Proof of Lemma 10.4** First observe that if  $u_t < u_{xx}$  in  $Q_T^{a,b}$ , then  $u$  cannot have a (local or global) maximum in  $Q_T^{a,b}$ . Indeed, if this maximum would be situated at  $(x_0, t_0)$  with  $a < x_0 < b$  and  $0 < t_0 < T$ , then at  $(x, t) = (x_0, t_0)$  one has  $u_{xx} > u_t = u_x = 0$ , contradiction. Also a maximum at  $(x_0, T)$  is impossible because then  $u_{xx} > u_t \geq 0$ , again a contradiction.

Next we reduce the case  $u_t \leq u_{xx}$  to  $u_t < u_{xx}$ . Let

$$u_n(x, t) = u(x, t) + \frac{x^2}{2n}.$$

Then obviously

$$u_{nt} = u_t \leq u_{xx} < u_{xx} + \frac{1}{n} = u_{nxx},$$

so that

$$\sup_{Q_T^{a,b}} u_n = \max_{\Gamma_T^{a,b}} u_n.$$

Taking the limit  $n \rightarrow \infty$  the lemma follows. ■

**Proof of Lemma 10.3** It is sufficient to prove the statement for one fixed  $T > 0$ . For  $\alpha, \beta, \gamma > 0$  let

$$h(x, t) = \exp\left(\frac{\alpha x^2}{1 - \beta t} + \gamma t\right) \quad x \in \mathbb{R}, \quad 0 \leq t < \frac{1}{\beta}.$$

Define  $u(x, t)$  by  $u = hv$ . Then

$$0 \geq u_t - u_{xx} = (hv)_t - (hv)_{xx} = hv_t + h_tv - hv_{xx} - 2h_xv_x - h_{xx}v =$$

$$h(v_t - v_{xx} - v_x \frac{2h_x}{h} + v \frac{h_t - h_{xx}}{h}) =$$

$$h\left(v_t - v_{xx} - v_x \frac{4\alpha x}{1 - \beta t} + v\left(\frac{\alpha\beta x^2}{(1 - \beta t)^2} + \gamma - \left(\frac{2\alpha x}{1 - \beta t}\right)^2 - \frac{2\alpha}{1 - \beta t}\right)\right) =$$

$$h\left(v_t - v_{xx} - \frac{4\alpha x}{1 - \beta t}v_x + v\left(\gamma - \frac{(4\alpha - \beta)\alpha x^2}{(1 - \beta t)^2} - \frac{2\alpha}{1 - \beta t}\right)\right). \quad (9.6)$$

Choosing  $\beta > 4\alpha$  and  $\gamma > 4\alpha$  the coefficient of  $v$  is positive for  $x \in \mathbb{R}$  and  $0 \leq t \leq 1/2\beta$ . We then also have

$$v(x, t) = u(x, t)\exp\left(-\frac{\alpha x^2}{1 - \beta t} - \gamma t\right) \leq Ae^{(B-\alpha)x^2},$$

so that, choosing  $\alpha > B$ ,

$$\limsup_{|x| \rightarrow \infty} v(x, t) \leq 0 \quad \text{uniformly on } [0, \frac{1}{2\beta}]. \quad (9.7)$$

Now suppose the lemma is false for  $T = 1/2\beta$ . Then  $u$  and  $v$  achieve positive values on  $Q_{1/2\beta}$ . In view (9.7) this implies that  $v$  must have a positive maximum in  $Q_{1/2\beta}$ . By the inequality for  $u_t - u_{xx}$  and the choice of  $\alpha, \beta, \gamma$  this implies  $v_t < v_{xx}$  at this maximum. But in the proof of Lemma 10.4 we have seen that this is impossible, contradiction. ■

**10.5 Exercise** Finish the uniqueness proof. ■

**10.6 Exercise** For  $u_0 \in C(\mathbb{R})$  satisfying

$$|u_0(x)| \leq Ae^{Bx^2}$$

for all  $x \in \mathbb{R}$ , prove that (CP) has a classical solution  $u \in C^{2,1}(Q_T) \cap C(\overline{Q}_T)$  for all  $T < 1/4B$ , and give a growth condition which determines the solution uniquely.

Next we consider the equation

$$u_t = u_{xx} + \varphi \quad x \in \mathbb{R}, \quad 0 < t \leq T,$$

where  $\varphi : \mathbb{R} \times (0, T) \rightarrow \mathbb{R}$ . If  $\varphi$  is measurable and bounded, we can try as a particular solution

$$u_p(x, t) = \int_0^t \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \varphi(\xi, \tau) d\xi d\tau. \quad (9.8)$$

Clearly,  $u_p$  is well defined, because the integral is dominated by

$$\int_0^t \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \sup_{Q_T} |\varphi| d\xi d\tau \leq t \sup_{Q_T} |\varphi|,$$

so that in particular  $u_p(x, t) \rightarrow 0$  uniformly in  $x$  as  $t \downarrow 0$ .

One would like to have  $u_p \in C^{2,1}(Q_T)$ , which is however rather technical to establish and unfortunately requires more than just the continuity of  $\varphi$ . Here we just restrict ourselves to

**10.7 Proposition** Let  $\varphi \in L^\infty(Q_T)$ . Then

$$u_p(x, t) = \int_0^t \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \varphi(\xi, \tau) d\xi d\tau$$

defines a bounded function which is a solution of  $u_t = u_{xx} + \varphi$  in the sense of distributions on  $\mathbb{R} \times (0, T)$ , and tends to zero uniformly on  $\mathbb{R}$  as  $t \downarrow 0$ .

**Proof** If we set  $E^+(x, t) \equiv \varphi(x, t) \equiv 0$  for all  $t < 0$ , then

$$u_p(x, t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \varphi(\xi, \tau) d\xi d\tau.$$

Let  $\psi \in D(\mathbb{R} \times (0, T))$ , and extend  $\psi$  to  $\mathbb{R} \times \mathbb{R}$  by  $\psi(x, t) \equiv 0$  for  $t \leq 0$  and  $t \geq T$ . Then

$$\begin{aligned} & \left\langle \frac{\partial u_p}{\partial t} - \frac{\partial^2 u_p}{\partial x^2}, \psi \right\rangle = - \left\langle u_p, \psi_t + \psi_{xx} \right\rangle = \\ & - \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \varphi(\xi, \tau) (\psi_t(x, t) + \psi_{xx}(x, t)) d\xi d\tau dx dt = \\ & - \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \left\{ \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) (\psi_t(x, t) + \psi_{xx}(x, t)) dx dt \right\} \varphi(\xi, \tau) d\xi d\tau = \end{aligned}$$

(as in the proof that  $E^+$  is a fundamental solution)

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \varphi(\xi, \tau) \psi(\xi, \tau) d\xi d\tau = \langle \varphi, \psi \rangle,$$

so that  $u_p$  is a solution of the inhomogeneous heat equation in the sense of distributions. ■

We can now write down the solution of

$$(CP_i) \quad \begin{cases} u_t = u_{xx} + \varphi & x \in \mathbb{R}, t > 0; \\ u(x, 0) = u_0(x) & x \in \mathbb{R}, \end{cases}$$

as

$$u(x, t) = \int_{-\infty}^{\infty} E^+(x - \xi, t) u_0(\xi) d\xi + \int_0^t \int_{-\infty}^{\infty} E^+(x - \xi, t - \tau) \varphi(\xi, \tau) d\xi d\tau,$$

but we do not give the precise hypothesis here on  $u_0$  and  $\varphi$  that guarantee that this formula defines a *classical* solution, i.e.

$$u \in C^{2,1}(\mathbb{R} \times \mathbb{R}^+) \cap C(\overline{\mathbb{R}} \times \overline{\mathbb{R}}^+).$$

**10.8 Exercise** Show that  $(CP_i)$  has at most one bounded classical solution.

## 11. Initial boundary value problems

First we indicate how one can generalize results for

$$(CP) \begin{cases} u_t = u_{xx} & x \in \mathbb{R}, t > 0; \\ u(x, 0) = u_0(x) & x \in \mathbb{R}, \end{cases}$$

to

$$(CD) \begin{cases} u_t = u_{xx} & x > 0, t > 0; \\ u(0, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & x \geq 0, \end{cases}$$

and

$$(CN) \begin{cases} u_t = u_{xx} & x > 0, t > 0; \\ u_x(0, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & x \geq 0. \end{cases}$$

For (CD) and (CN) we consider (CP) with odd and even initial data respectively.

We begin with (CD). Extending  $u_0$  to the whole of  $\mathbb{R}$  by  $u_0(-x) = -u_0(x)$ , the integral representation of solutions gives

$$\begin{aligned} u(x, t) &= - \int_{-\infty}^0 E^+(x - \xi, t) u_0(-\xi) d\xi + \int_0^{\infty} E^+(x - \xi, t) u_0(\xi) d\xi = \\ &= \int_0^{\infty} \{E^+(x - \xi, t) - E^+(x + \xi, t)\} u_0(\xi) d\xi = \int_0^{\infty} G_1(x, \xi, t) u_0(\xi) d\xi, \end{aligned} \quad (11.1)$$

where

$$G_1(x, \xi, t) = E^+(x - \xi, t) - E^+(x + \xi, t) \quad (11.2)$$

is called the *Green's function of the first kind*.

For (CN) we extend  $u_0$  by  $u_0(-x) = u_0(x)$ , and thus

$$\begin{aligned} u(x, t) &= \int_{-\infty}^0 E^+(x - \xi, t) u_0(-\xi) d\xi + \int_0^{\infty} E^+(x - \xi, t) u_0(\xi) d\xi = \\ &= \int_0^{\infty} \{E^+(x - \xi, t) + E^+(x + \xi, t)\} u_0(\xi) d\xi = \int_0^{\infty} G_2(x, \xi, t) u_0(\xi) d\xi, \end{aligned} \quad (11.3)$$

where

$$G_2(x, \xi, t) = E^+(x - \xi, t) + E^+(x + \xi, t) \quad (11.3)$$

is called the *Green's function of the second kind*.

**11.1 Exercise** Let  $u_0 \in C(\overline{\mathbb{R}^+})$  be bounded, and let  $u_0(0) = 0$ . Prove that  $(CD)$  has a unique bounded solution  $u \in C^{2,1}(\mathbb{R}^+ \times \mathbb{R}^+) \cap C(\overline{\mathbb{R}^+} \times \overline{\mathbb{R}^+})$ .

**11.2 Exercise** Let  $u_0 \in C(\overline{\mathbb{R}^+})$  be bounded. Prove that  $(CN)$  has a unique bounded solution  $u \in C^{2,1}(\overline{\mathbb{R}^+} \times \mathbb{R}^+) \cap C(\overline{\mathbb{R}^+} \times \overline{\mathbb{R}^+})$ .

**11.3 Exercise** Derive formal integral representations for the solutions of

$$(CD_i) \begin{cases} u_t = u_{xx} + \varphi & x > 0, t > 0; \\ u(0, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & x \geq 0, \end{cases}$$

and

$$(CN_i) \begin{cases} u_t = u_{xx} + \varphi & x > 0, t > 0; \\ u_x(0, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & x \geq 0. \end{cases}$$

Next we consider what is usually called the *Dirichlet problem* for the heat equation on  $(0, 1)$ :

$$(D) \begin{cases} u_t = u_{xx} & 0 < x < 1, t > 0; \\ u(0, t) = u(1, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & 0 \leq x \leq 1. \end{cases}$$

To find an integral representation for the solution of  $(D)$  we extend  $u_0$  to a 2-periodic function  $\tilde{u}_0 : \mathbb{R} \rightarrow \mathbb{R}$  defined by

$$\tilde{u}_0 \equiv u_0 \text{ on } (0, 1); \quad \tilde{u}_0(x) = -\tilde{u}_0(-x); \quad \tilde{u}_0(1+x) = -\tilde{u}_0(1-x).$$

For the Cauchy problem with initial data  $\tilde{u}_0$  we then have

$$\begin{aligned} u(x, t) &= \int_{-\infty}^{\infty} E^+(x - \xi, t) \tilde{u}_0(\xi) d\xi = \sum_{k=-\infty}^{\infty} \int_k^{k+1} E^+(x - \xi, t) \tilde{u}_0(\xi) d\xi = \\ &= \sum_{k=-\infty}^{\infty} \int_0^1 E^+(x - \xi - k, t) \tilde{u}_0(\xi + k) d\xi = \\ &= \sum_{n=-\infty}^{\infty} \left\{ \int_0^1 E^+(x - \xi - 2n, t) \tilde{u}_0(\xi + 2n) d\xi + \int_0^1 E^+(x - \xi - 2n - 1, t) \tilde{u}_0(\xi + 2n + 1) d\xi \right\} = \\ &= \sum_{n=-\infty}^{\infty} \left\{ \int_0^1 E^+(x - \xi - 2n, t) \tilde{u}_0(\xi) d\xi + \int_0^1 E^+(x - \xi - 2n - 1, t) \tilde{u}_0(\xi + 1) d\xi \right\} = \\ &= \sum_{n=-\infty}^{\infty} \left\{ \int_0^1 E^+(x - \xi - 2n, t) \tilde{u}_0(\xi) d\xi - \int_0^1 E^+(x - \xi - 2n - 1, t) \tilde{u}_0(1 - \xi) d\xi \right\} = \end{aligned}$$



$$\begin{aligned}
& \sum_{n=-\infty}^{\infty} \left\{ \int_0^1 E^+(x - \xi - 2n, t) \tilde{u}_0(\xi) d\xi - \int_0^1 E^+(x + \xi - 1 - 2n - 1, t) \tilde{u}_0(\xi) d\xi \right\} \\
&= \int_0^1 \sum_{n=-\infty}^{\infty} \{ E^+(x - \xi - 2n, t) - E^+(x + \xi - 2n, t) \} \tilde{u}_0(\xi) d\xi \\
&= \int_0^1 G_D(x, \xi, t) \tilde{u}_0(\xi) d\xi,
\end{aligned} \tag{11.4}$$

where

$$G_D(x, \xi, t) = \sum_{n=-\infty}^{\infty} \{ E^+(x - \xi - 2n, t) - E^+(x + \xi - 2n, t) \}. \tag{11.5}$$

(Note that this sum is absolutely convergent for  $t > 0$ , uniformly in  $x$ .)

**11.4 Theorem** Let  $u_0 \in C([0, 1])$ ,  $u_0(0) = u_0(1) = 0$ , and let  $Q_T = (0, 1) \times (0, T]$ . Then for every  $T > 0$  there exists a unique bounded solution  $u \in C^{2,1}(Q_T) \cap C(\bar{Q}_T)$  of (D), given by

$$u(x, t) = \int_0^1 G_D(x, \xi, t) u_0(\xi) d\xi.$$

**Proof** Exercise, for the uniqueness part, the maximum principle has to be used again. ■

$G_D$  is called the *Green's function for the Dirichlet problem*.

For the *Neumann problem*, that is

$$(N) \begin{cases} u_t = u_{xx} & 0 < x < 1, \ t > 0; \\ u_x(0, t) = u_x(1, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & 0 \leq x \leq 1, \end{cases}$$

we extend  $u_0$  to a 2-periodic function  $\tilde{u}_0 : \mathbb{R} \rightarrow \mathbb{R}$  by

$$\tilde{u}_0 \equiv u_0 \text{ on } [0, 1]; \quad \tilde{u}_0(x) = \tilde{u}_0(-x); \quad \tilde{u}_0(1+x) = \tilde{u}_0(1-x).$$

We now obtain

$$u(x, t) = \int_0^1 G_N(x, \xi, t) u_0(\xi) d\xi, \tag{11.6}$$

where

$$G_N(x, \xi, t) = \sum_{n=-\infty}^{\infty} \{ E^+(x - \xi - 2n, t) + E^+(x + \xi - 2n, t) \} \tag{11.7}$$

is *Green's function for the Neumann problem*.

**11.5 Theorem** Let  $u_0 \in C([0, 1])$ . Then for every  $T > 0$  there exists a unique bounded classical solution of (N), given by

$$u(x, t) = \int_0^1 G_N(x, \xi, t) u_0(\xi) d\xi.$$

**11.6 Exercise** Give a suitable definition of a classical solution of (N) and prove this theorem.

**11.7 Exercise** Derive a representation formula for solutions of the mixed problem

$$(DN) \begin{cases} u_t = u_{xx} & 0 < x < 1, \ t > 0; \\ u(0, t) = u_x(1, t) = 0 & t > 0; \\ u(x, 0) = u_0(x) & 0 \leq x \leq 1, \end{cases}$$

and formulate and prove a uniqueness/existence theorem.

**11.8 Exercise** Give formal derivations for integral representations of solutions to the problems above with  $u_t = u_{xx}$  replaced by the inhomogeneous equation  $u_t = u_{xx} + \varphi$ .

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